

Rebecca E. Schwartz

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Education

Master of Engineering in Mechanical Engineering | Control of Robotic and Autonomous Systems | May 2020
Fung Institute for Engineering Leadership | College of Engineering | University of California, Berkeley | GPA: 3.77

Bachelor of Science in Mechanical Engineering | Minor in Engineering Management | June 2019
Pennoni Honors College | College of Engineering | Drexel University, Philadelphia, PA | GPA: 3.58

Projects

Sensor Robots for Emergency Response: Centrally Actuated Mobile Robot Sept. 2019 - July 2020

- Led hardware assembly to build Squishy Robotics' first centrally actuated tensegrity mobile robot, "Flounder"
- Enabled face-to-face motor control using Dijkstra's shortest path algorithm and an IMU for Flounder
- Hired as a full time Mechatronics Engineering Intern for May - July 2020
 - Optimized GUI for the centrally actuated tensegrity mobile robot, taking into consideration potential future design choices
 - Assembled the company's next flagship mobile tensegrity robot, MR3 (dremeling, assembly of electro-mechanical parts)

Advanced Controls

Controlling a Simulated Landing of the SpaceX Starship Rocket on Mars Dec. 2019

- Simulated a rocket landing on Mars by implementing Model Predictive Control (MPC) with reference tracking
- Tested robustness via varying initial conditions and environmental disturbances

State Estimation of a Bicycle with the Extended Kalman Filter (EKF) Apr. 2020

- Designed an EKF in MATLAB to predict the final position of a bicycle despite various unknowns

Robotics

Low Level Control of a 3D Printed Pick and Place Robot Jan. - May 2020

- Controlled a 3D printed robot arm with a PSOC microcontroller, interfacing with C and LabVIEW
- Concepts Implemented: real-time, multitasking, interrupts, state machine, data communication

Pick and Place Challenge Jan. - March 2019

- Designed and built a 2P 3R Vex robot to compete in a pick-and-place challenge
- Coded and wired Arduino UNO in C++ to control all 5 selected motors using the serial monitor

Feedback Control with Optical Shaft Encoders Honors Project Jan. - March 2019

- Built a 2R robot to demonstrate feedback control using optical shaft encoders and Arduino UNO

Wearable Energy Harvesting Device Senior Design Project Sept. 2018 - May 2019

- Built wearable energy harvesting components using MXene coated yarns
- Engineered a yarn-coater for mass production of MXene coated yarns for knitted antennas with <\$100

Computer Vision Independent Side Project June - July 2019

- Implemented an image classifier with Google's GPU Compute Engine, Jupyter Notebook, and fastai
- Hand selected 150 impressionist paintings for training and testing, receiving a 67% success rate

Advanced Programming Jan. 2018 - June 2019

- Built and implemented an automatic file organizer in Unix
- Learned object-oriented programming (OOP), data structures, and algorithms

Computer Skills

Python, MATLAB, C++, C, AS (Kawasaki), LabVIEW, Bash/ Unix, AutoCAD, Creo, Revit, Excel, Jupyter/ Pytorch/ fastai

Professional Experience

Quality & Reliability Engineer | Kawasaki Robotics, San Jose, CA July 2020 - Present

- Leading reliability testing for the company's #1 priority project, for R&D of new flagship silicon-wafer handling robot
 - Wrote test programs in Kawasaki language; complete testing involving accelerometers, laser tracker, Keyence lasers
 - Analyze and present data to internal and external customers
- Perform quality assurance (QA) on silicon-wafer handling robots to ensure robot physical health
- Lead Failure Analyses (FA's), involving diagnosing, fixing, and writing detailed reports for customers
- Tuning robots to minimize vibration, acceleration, while maximizing silicon-wafer throughput

Mechanical Engineer Co-op | Bruce Brooks and Associates, Philadelphia, PA Apr. - Sept. 2018

- Designed mechanical and plumbing building systems using fluid mechanics and thermodynamics
- Drafted plumbing, fire protection, and mechanical systems for 10 projects in Revit

Formulations Engineer Co-op | FMC Corporation, Philadelphia, PA Apr. - Sept. 2017

- Managed the front end of a \$400K project to upgrade and relocate an insecticide packaging line
- Designed and implemented a scheme to minimize a biological cleanout's water usage by 42%

Leadership

- President of Drexel Honors Student Advisory Committee (HSAC) June 2018 - June 2019
- ITF Taekwondo Instructor July 2010 - Sept 2015

Coursework

Graduate

Experiential Advanced Control Design I,II
Advanced Controls
Design of Microprocessor-Based Mechanical Systems

Undergraduate

Dynamics; Controls I, II, Micro-controls
Intro to Robotics
Advanced Programming I, Data Structures